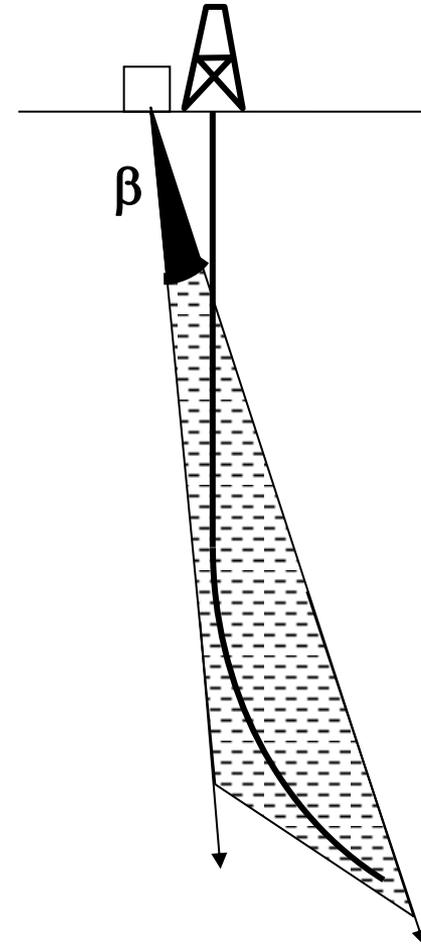
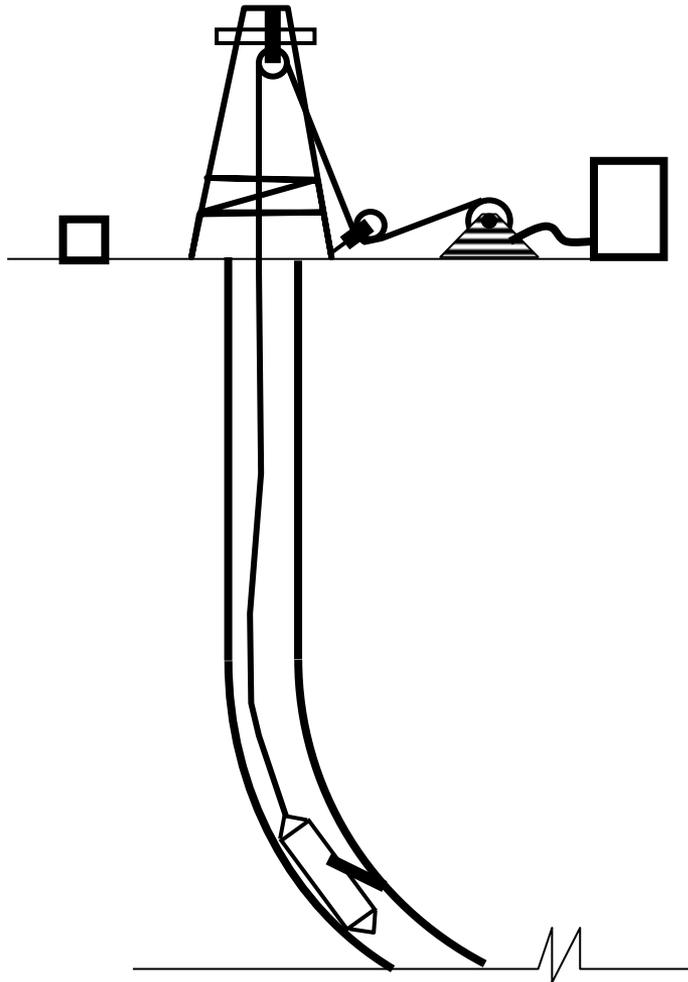


3C VSP data orientation method in vertical to low deviated borehole intervals, cased hole or open hole



3Component trihedron VSP data orientation in vertical to low deviated well intervals:

Fig.1

Configurations A or B represent the input 3C data orientation from field measurements.

Configuration C represents the output from the 3C data orientation preprocessing method

Configuration A: 3C data are recorded with a FIX 3 component sensor setting in VSP tool :

Z component in well axis, X, Y are orthogonal, in random direction versus depth

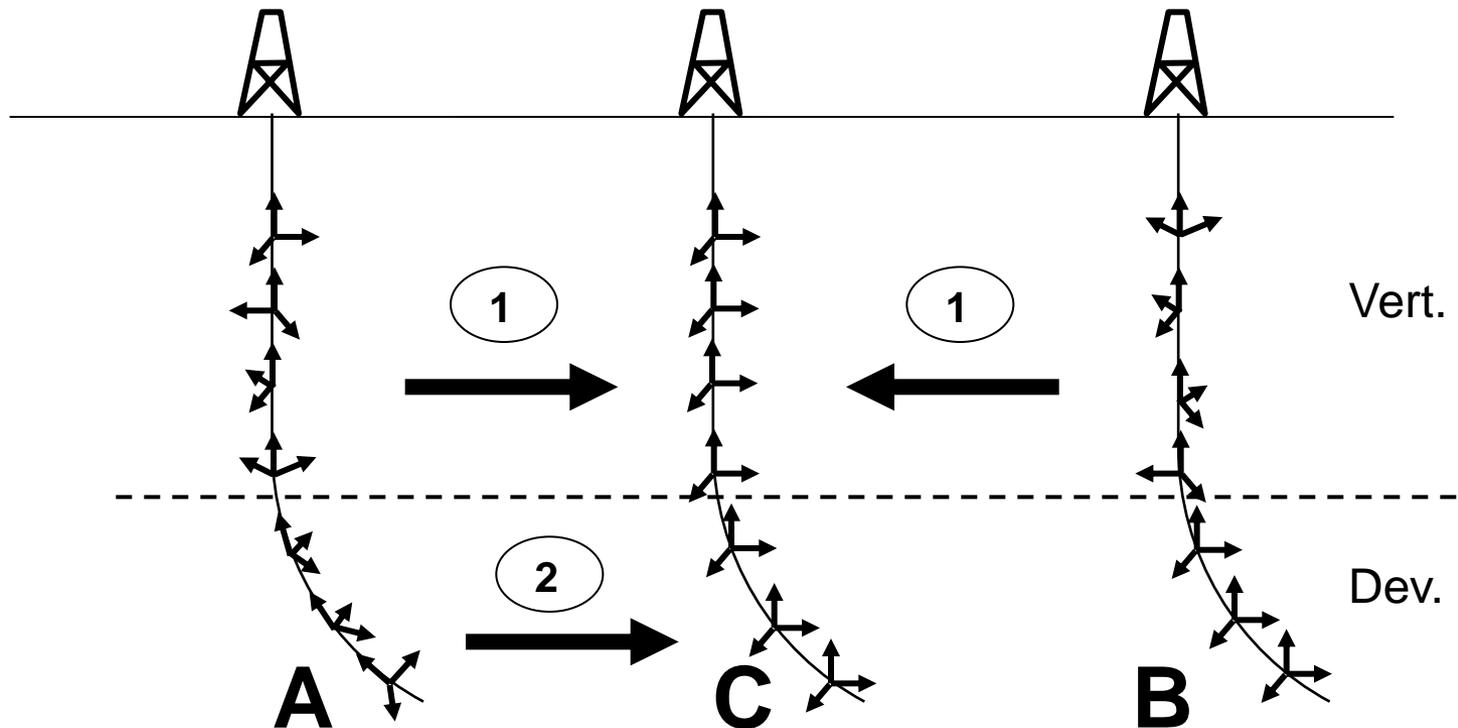
Configuration B: 3C data are recorded with a gimbal 3 component sensor setting in VSP tool :

Z component is vertical, X, Y are orthogonal, in random direction versus depth

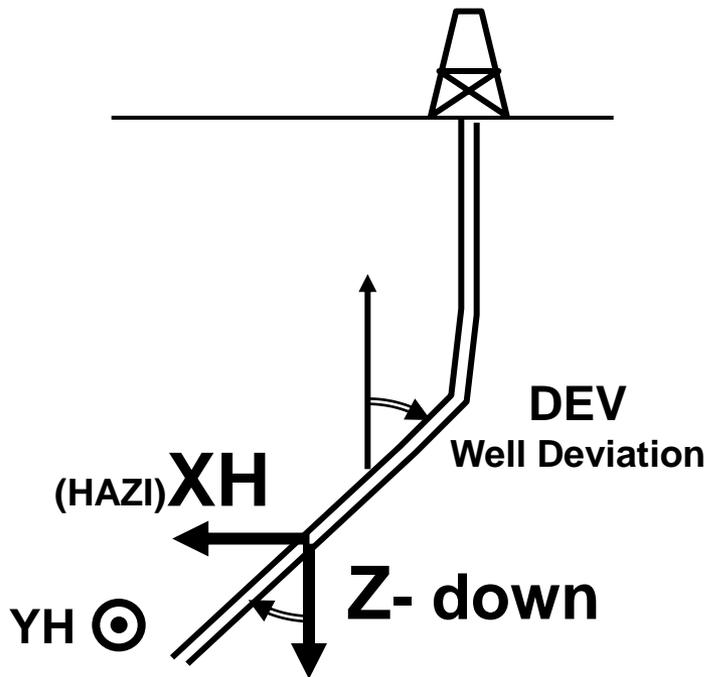
Configuration C: 3C data are oriented in a the SAME coordinate system for ALL depth stations:

Z component is vertical, X, Y are orthogonal, oriented in SAME azimuth, known or unknown, allowing

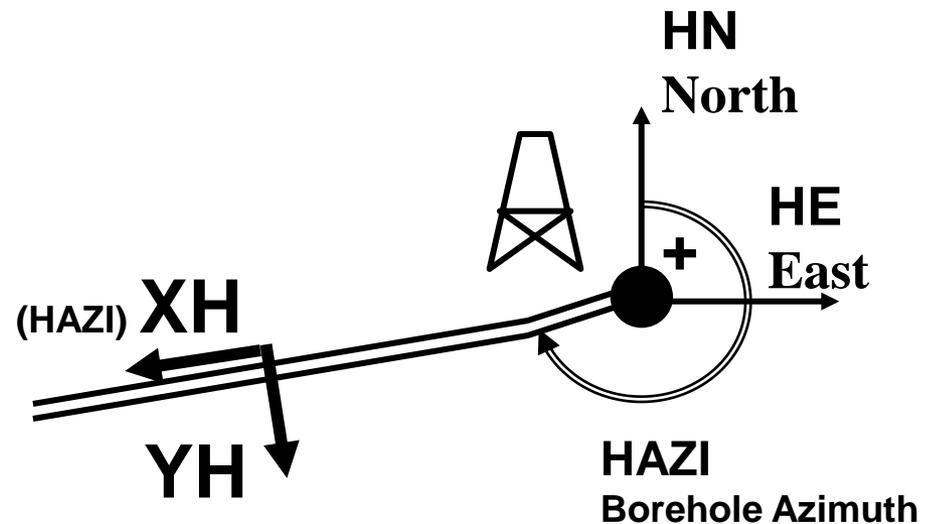
3C data processing: the X & Y azimuth is CALIBRATED into geographic direction using external information, from a tool orientation device, or geological knowledge of downdip azimuth from 3D surface seismic or other logs



**Orientation of components recorded Fig.2a
by the gimbal CSI tool in a deviated well**

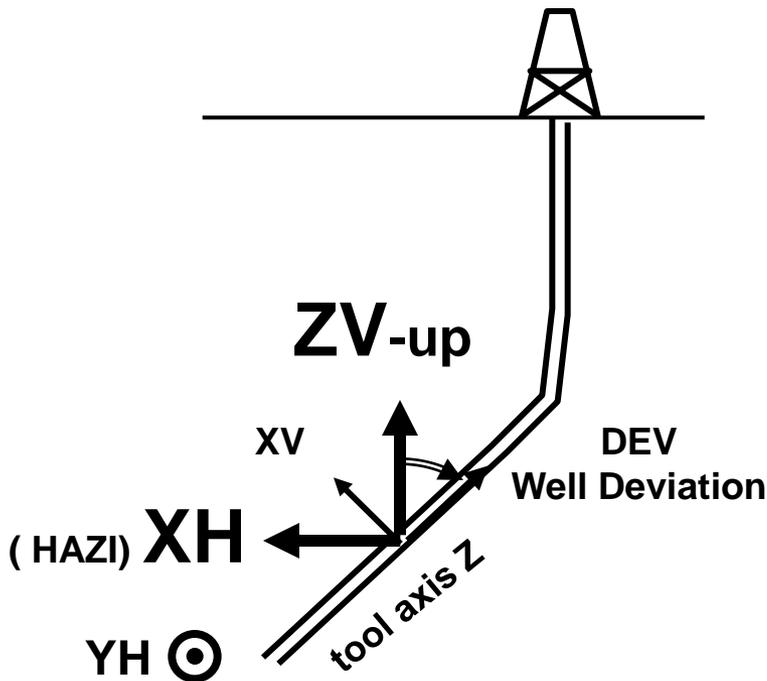


Vertical plane of deviation
tangent to borehole

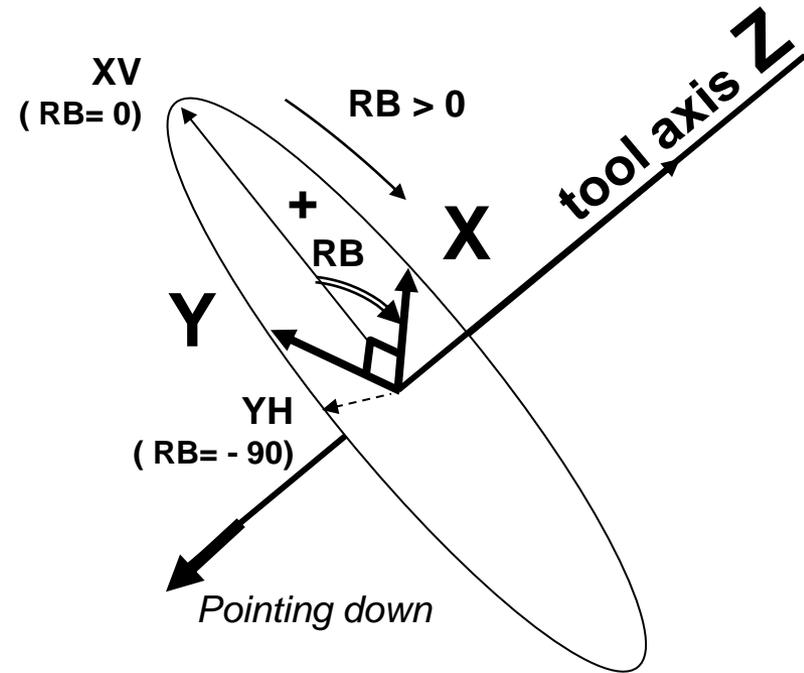


Horizontal plane, looking Down
[HN,HE] = Rot(-HAZI). [YH,XH]

Orientation of three fix components, Fig.2b of a VSI tool, with RB sensor, in a deviated well

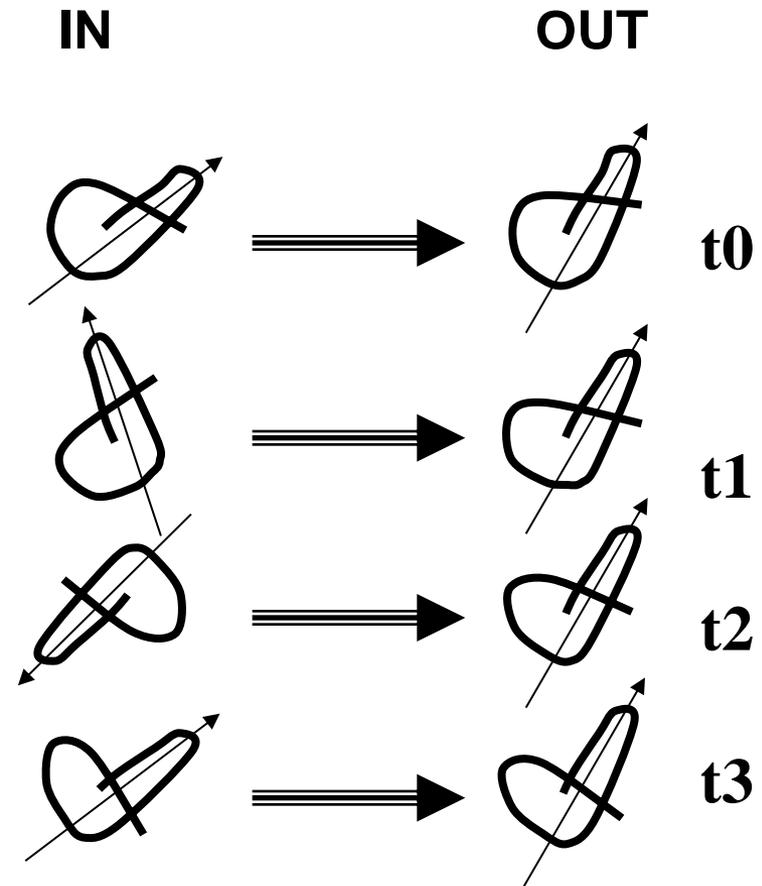
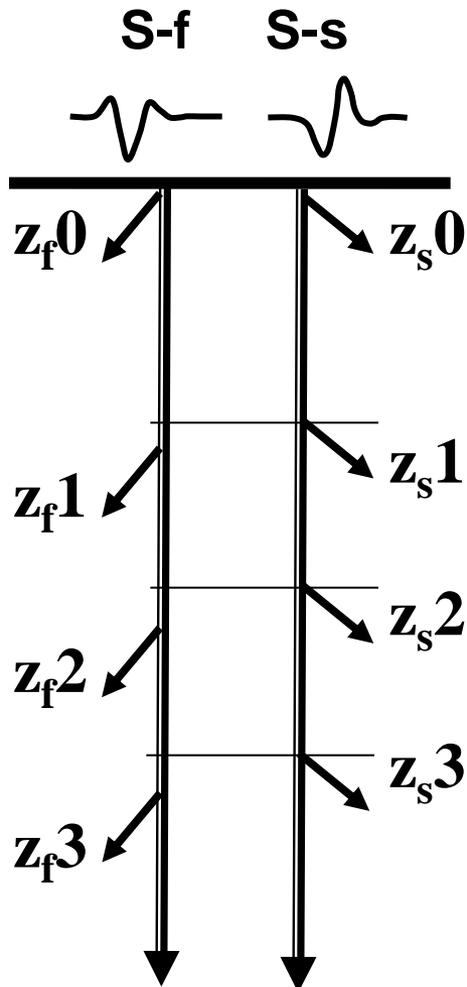


Vertical plane of deviation tangent to borehole:
 $[ZV\text{-up}, XH] = \text{Rot}(DEV). [Z, XV]$

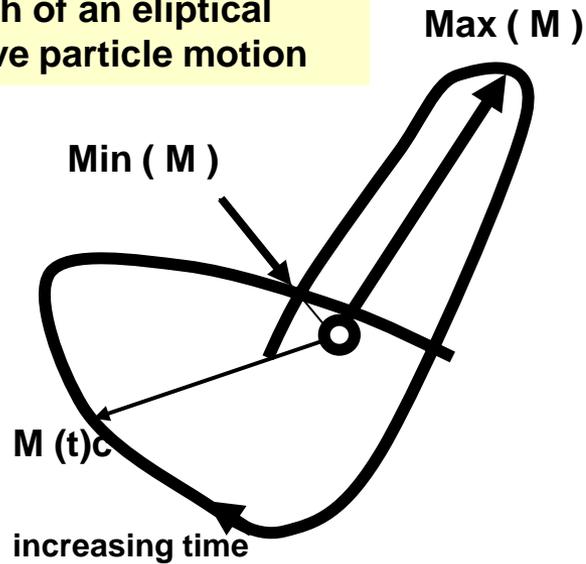


Relative Bearing angle illustration in plane orthogonal to well/tool axis
 $[XV, YH] = \text{Rot}(RB). [X, Y]$

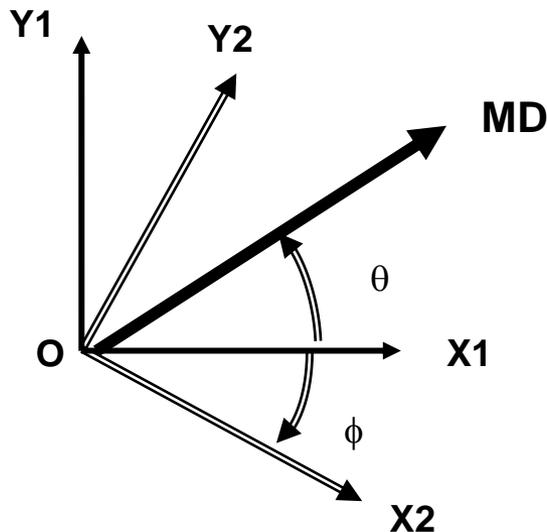
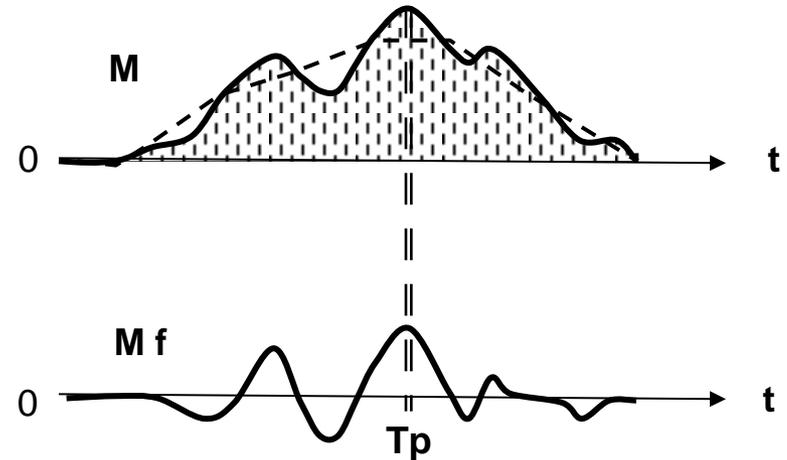
Principle: propagation of eigen modes of volumic seismic shear waves in semi-homogeneous medium



Sketch of an elliptical S-wave particle motion



Modulus trace , $M = \text{Raw (top)}$,
 $M_f = \text{LC filtered (bottom)}$



Modulus Vector MD coordinates in the X_1, Y_1 system:
 $MD = (X_1, Y_1)$ in cartesian coordinates
 $MD = [M, \theta]$ in polar coordinates

Modulus Vector MD coordinates in the X_2, Y_2 system:
 $MD = (X_2, Y_2)$ in cartesian coordinates
 $MD = [M, (\theta + \phi)]$ in polar coordinates

By definition, the amplitude of Modulus vector remains invariant versus coordinate system orientation, for any time sample :

therefore, the modulus trace $M(t)$ remains invariant versus coordinate system orientation, which allows to pick times accurately BEFORE orientation

FIRST Z-VSP orientation example,

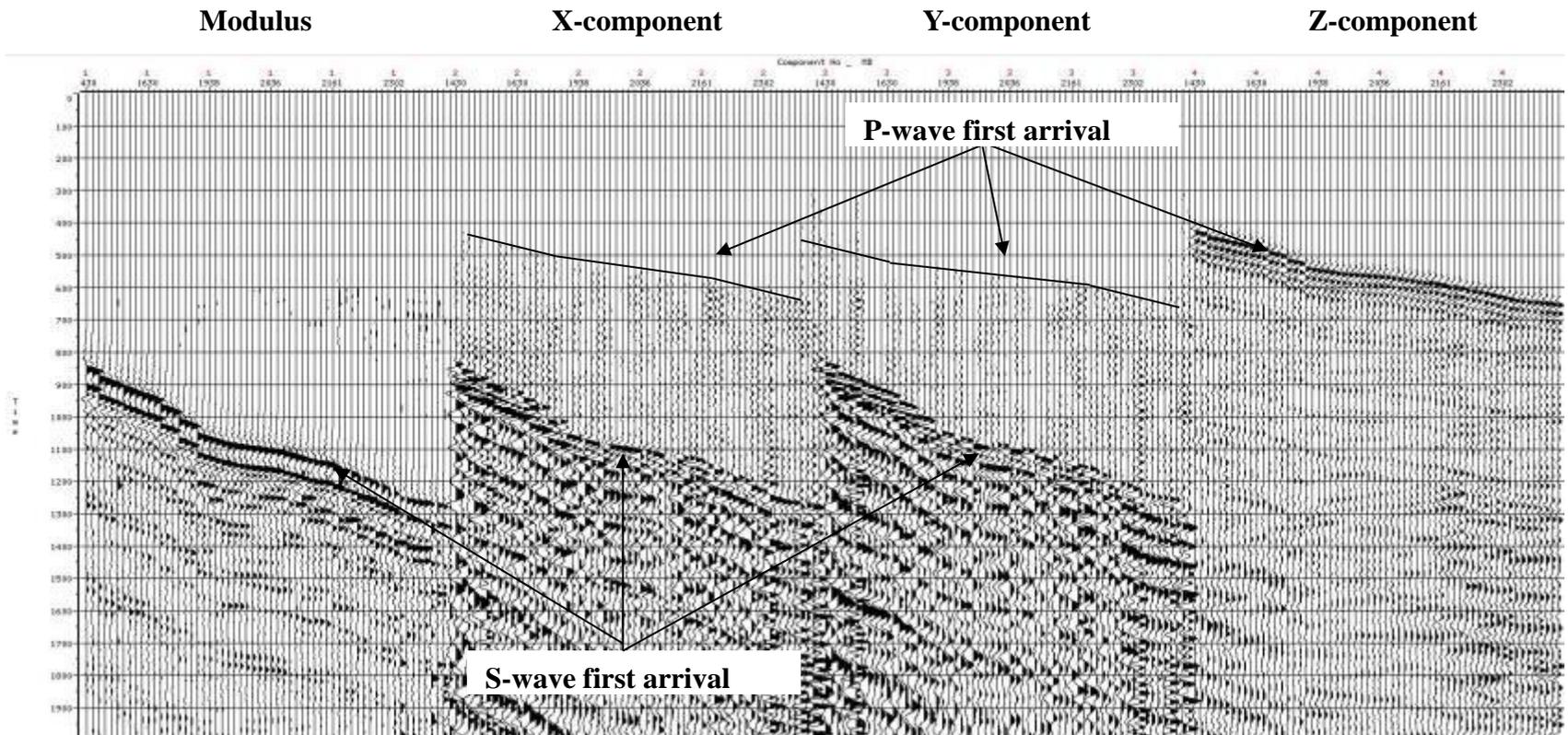
Ref. Kazem KAZEMI Ph-D thesis, Chapter 2, Chapter 6,

Seismic imaging of thrust fault structures in Zagros Iranian oil fields, from surface and well data.

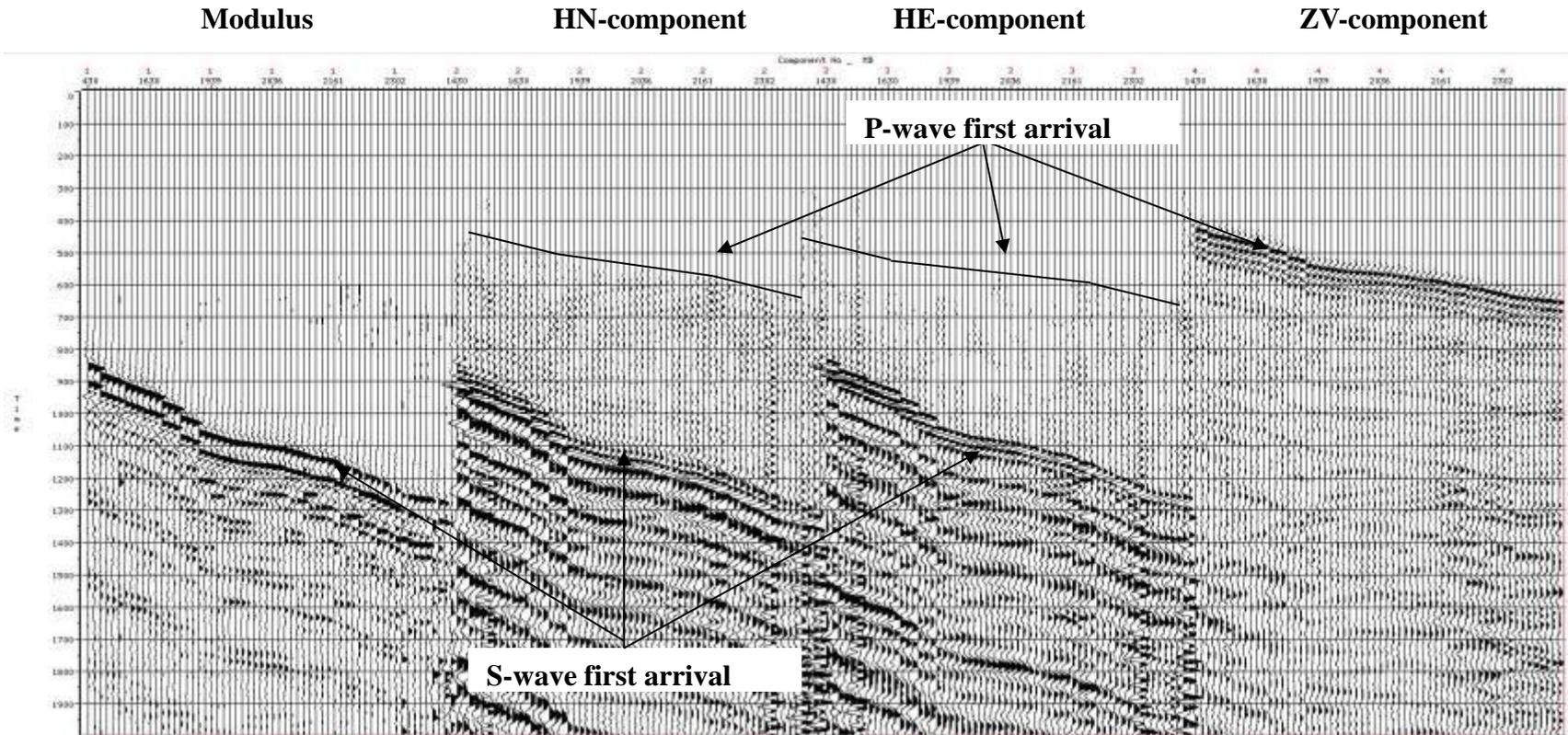
<https://tel.archives-ouvertes.fr/tel-00403617/> or

https://tel.archives-ouvertes.fr/file/index/docid/414628/filename/Thesis_kazemi.pdf

Modulus and three components **before** orientation



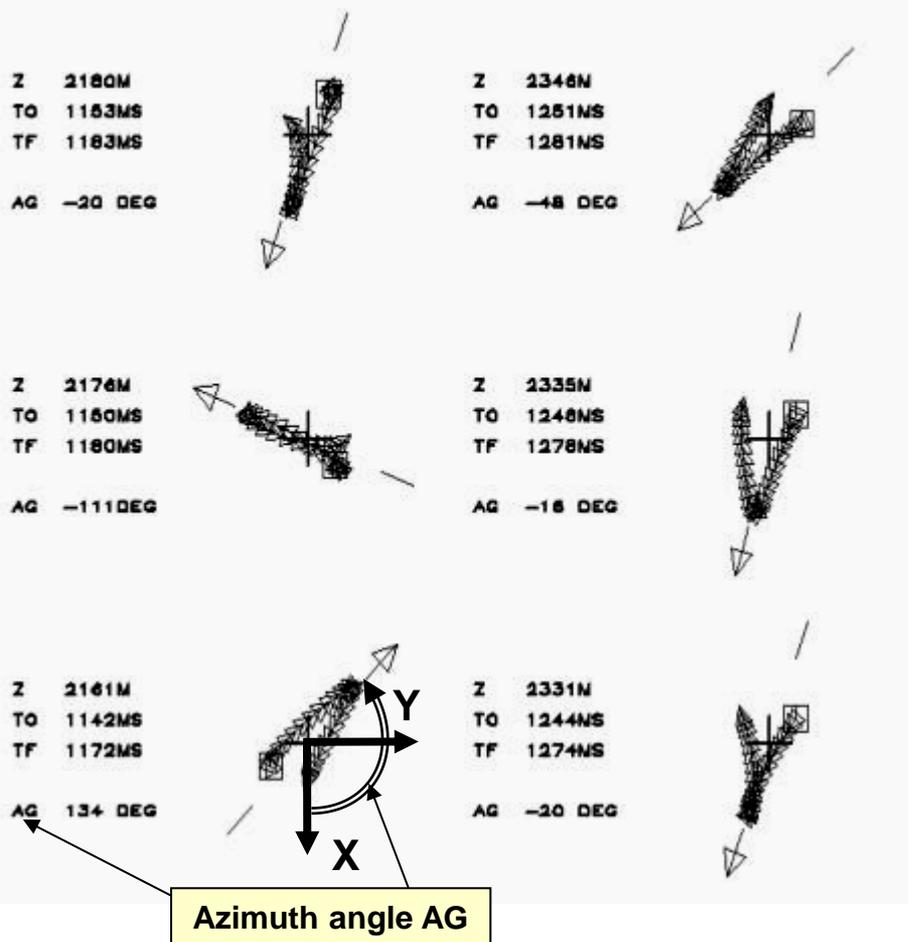
Modulus and three components **after** orientation



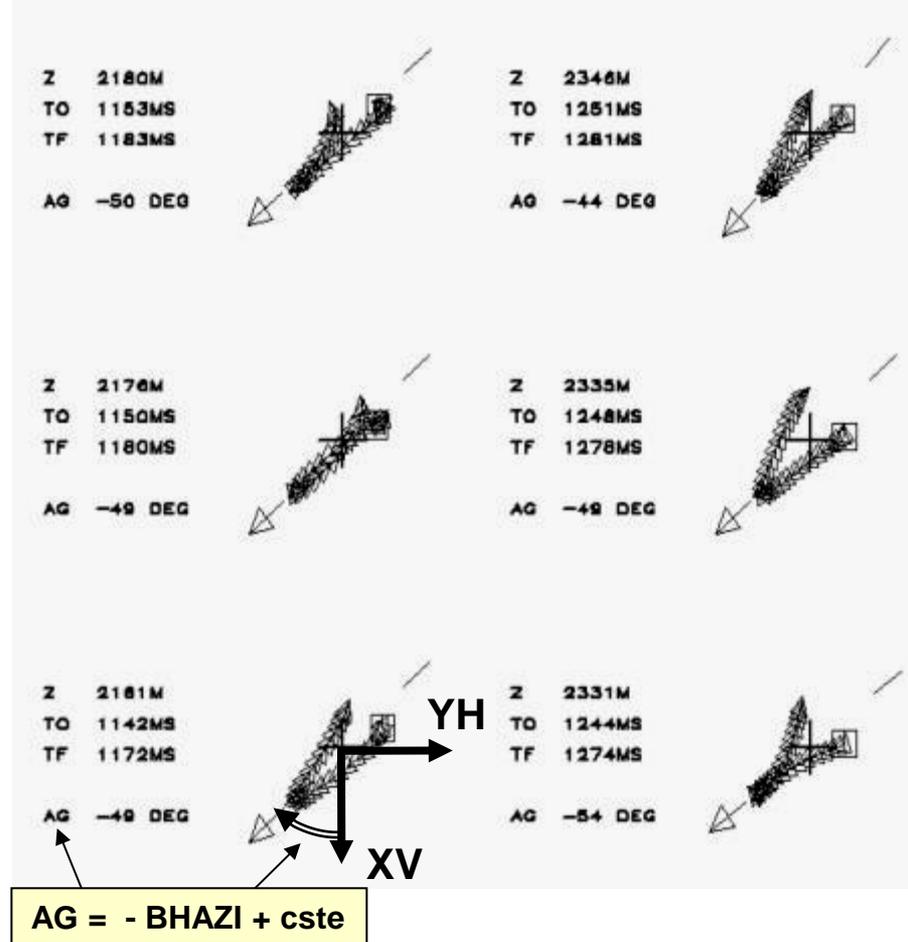
S-wave particle motion in short time window selected for maximization along S- first arrival picked on modulus trace.

By nature, the maximization direction occurs in a near- constant geographical azimuth

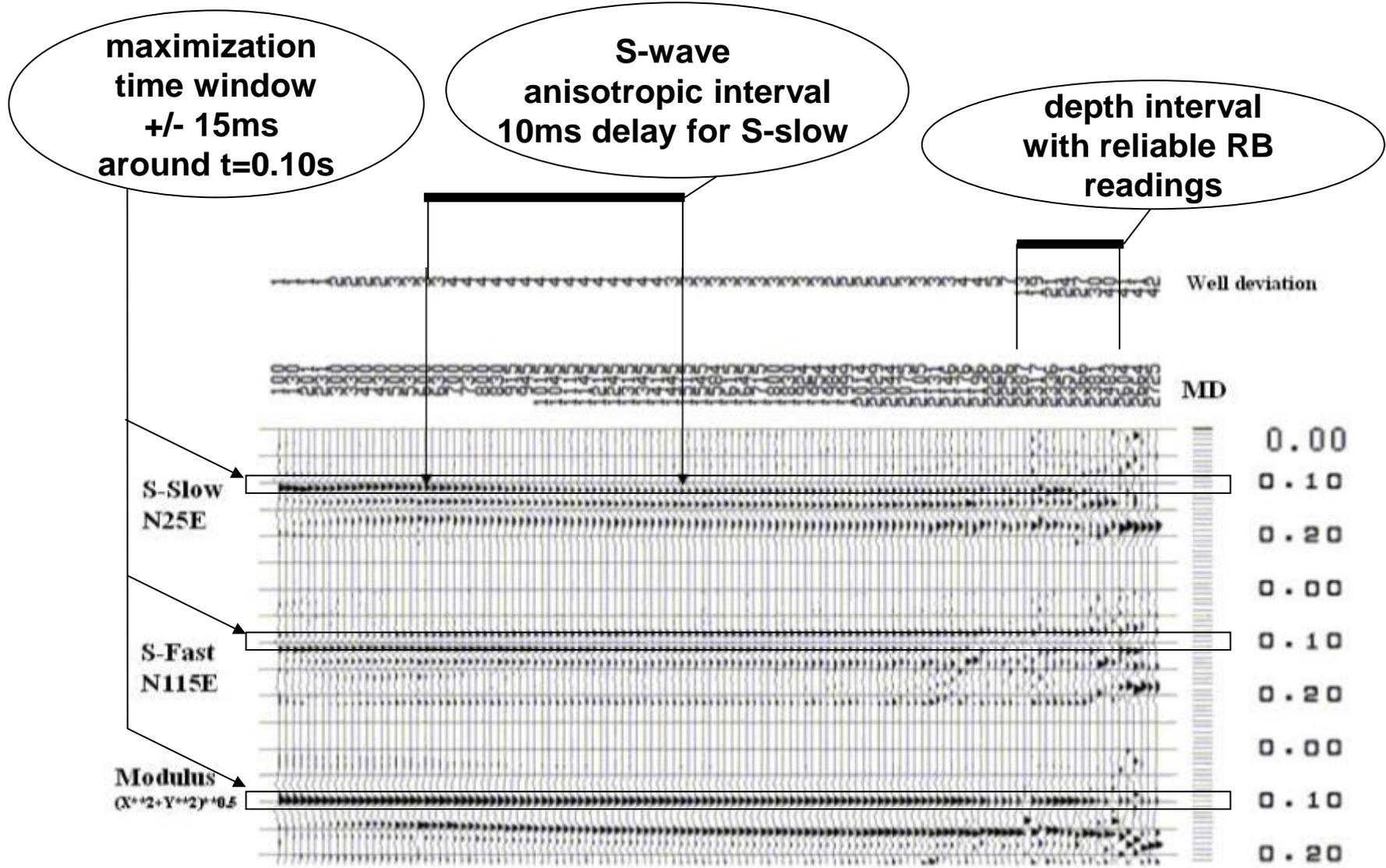
A) before orientation



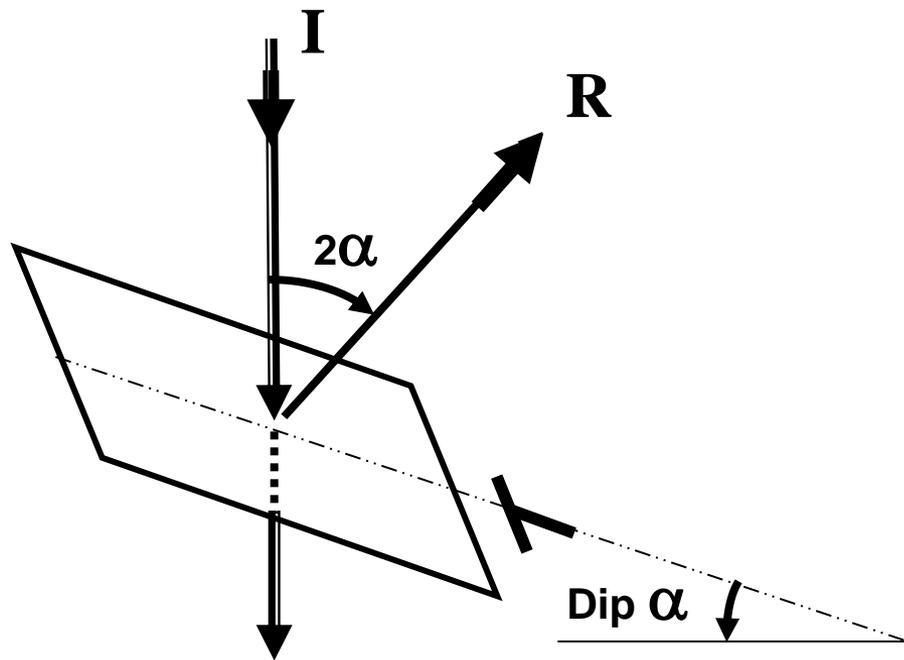
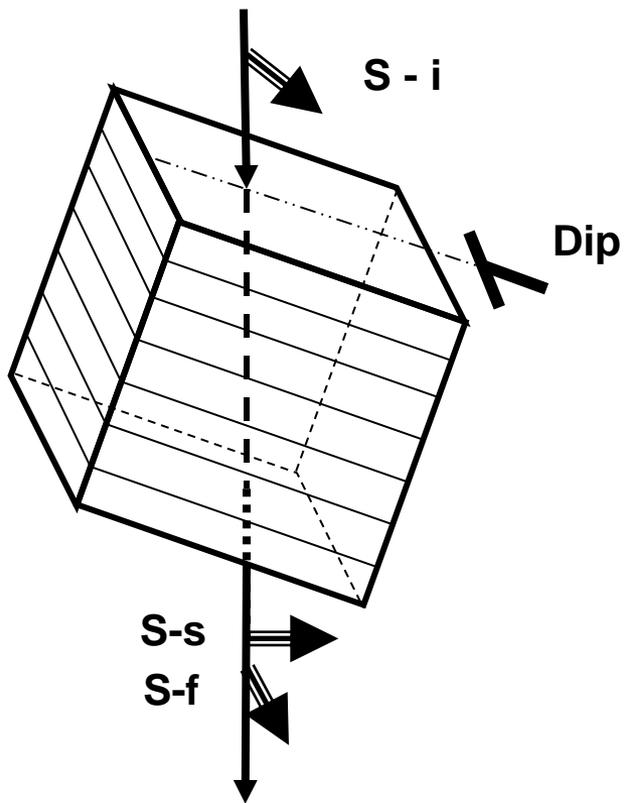
B) after orientation



S-fast, S-slow orthogonal components, from maximisation in a time window along the S-arrival time pick on filtered Modulus trace (bottom)



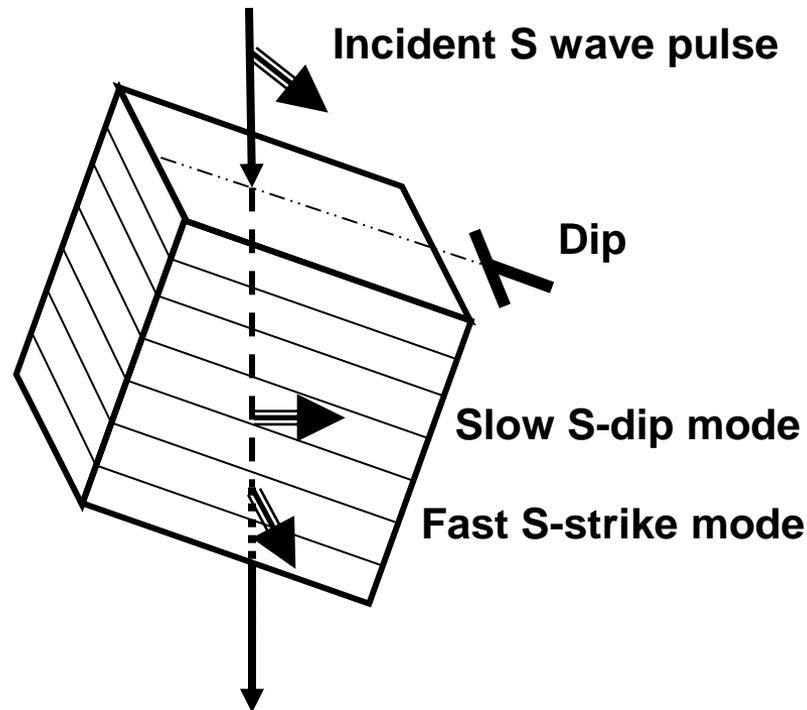
Courtesy of NIOC, IRAN



Vertical S-wave propagation in dipping layered medium

- Layering anisotropy induces the splitting of the incident S-wave into:
 - a) A fast horizontally polarized S-strike wave, in the strike direction parallel to layering.
 - b) A slow horizontally polarized S-dip wave, polarized in the azimuth of the dip
- Therefore the separation of the splitted direct S-wavetrain can help calibrate the azimuth trend of the general dip, when known from external structural information

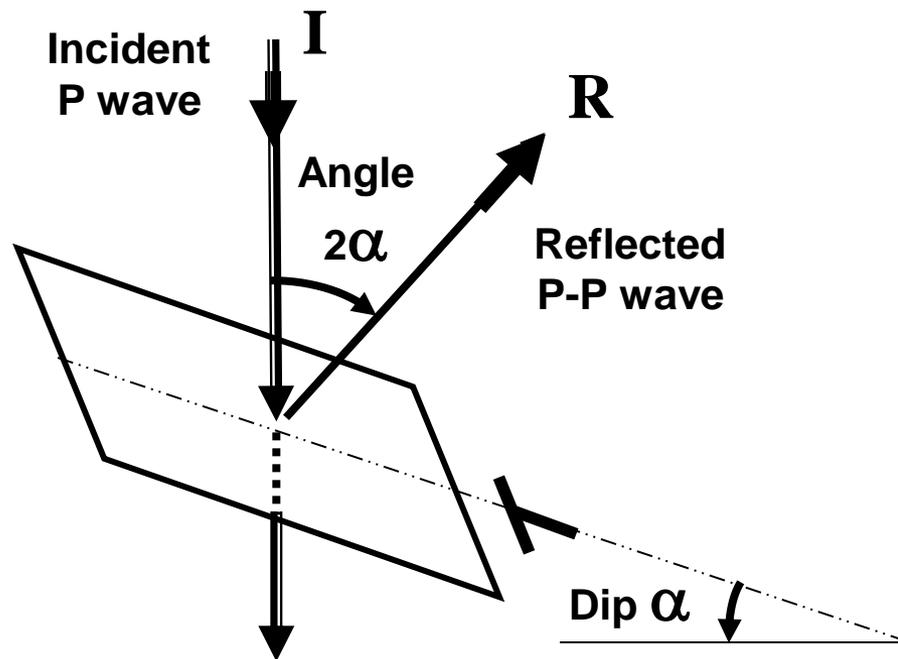
Vertical propagation for zero-offset VSP



Vertical P-wave propagation and dipping reflector

- The incident P-wave being is vertical and encounters a reflector dipping with angle (α),
- Then, the reflected P-P wave is polarized in the horizontal direction of the downdip azimuth of the reflector, $\pm 360^\circ$,
- The vertical incidence angle of the reflected P-P wave equals twice the dip angle (2α)
- Conversely, the dipping azimuth of a reflector determined from 3C VSP data previously oriented in a coherent coordinate system of unknown azimuth, can be used to calibrate the geographical orientation of the horizontal components of the initial VSP dataset

Vertical propagation
for zero-offset **VSP**



SECOND ZO-VSP orientation example,

Ref. Kazem KAZEMI Ph-D thesis, Chapter 7

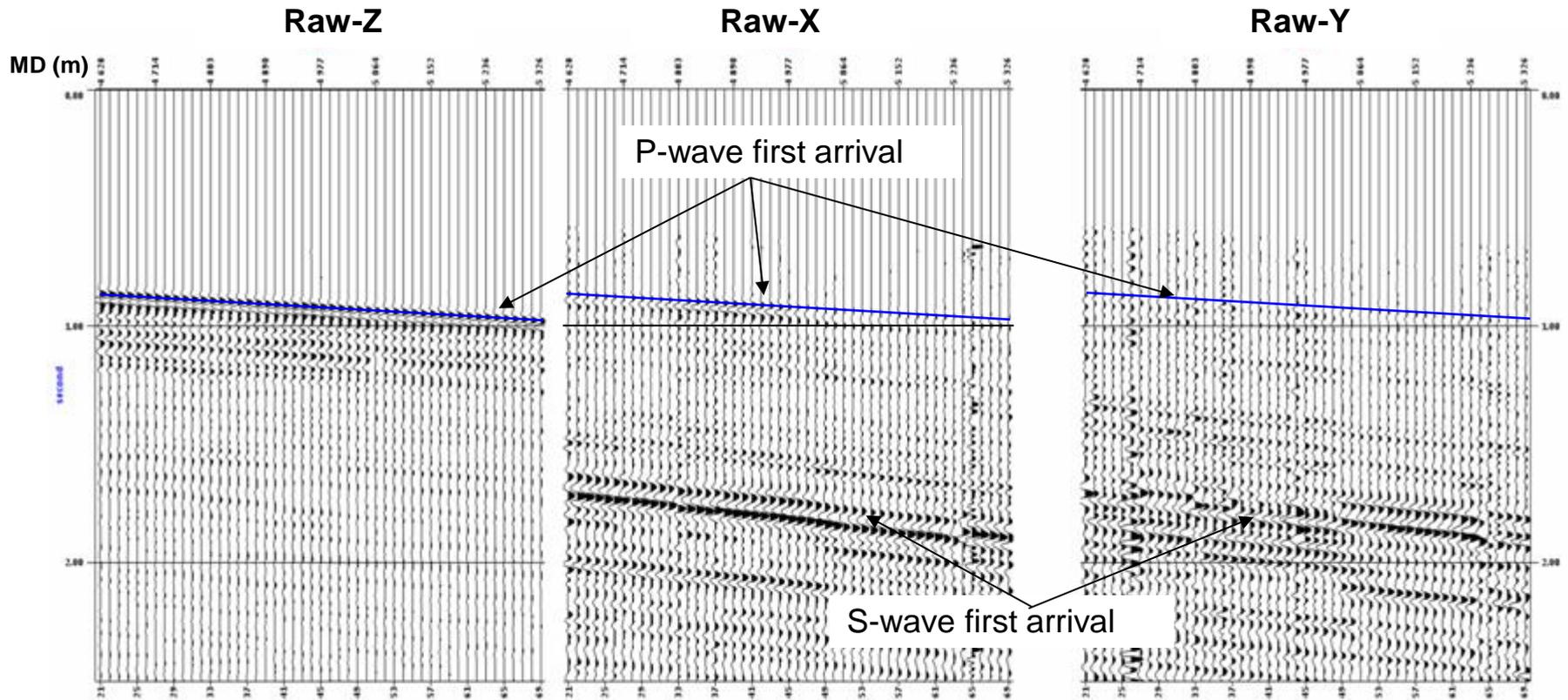
Seismic imaging of thrust fault structures in Zagros Iranian oil fields, from surface and well data.

<https://tel.archives-ouvertes.fr/tel-00403617/> or

https://tel.archives-ouvertes.fr/file/index/docid/414628/filename/Thesis_kazemi.pdf

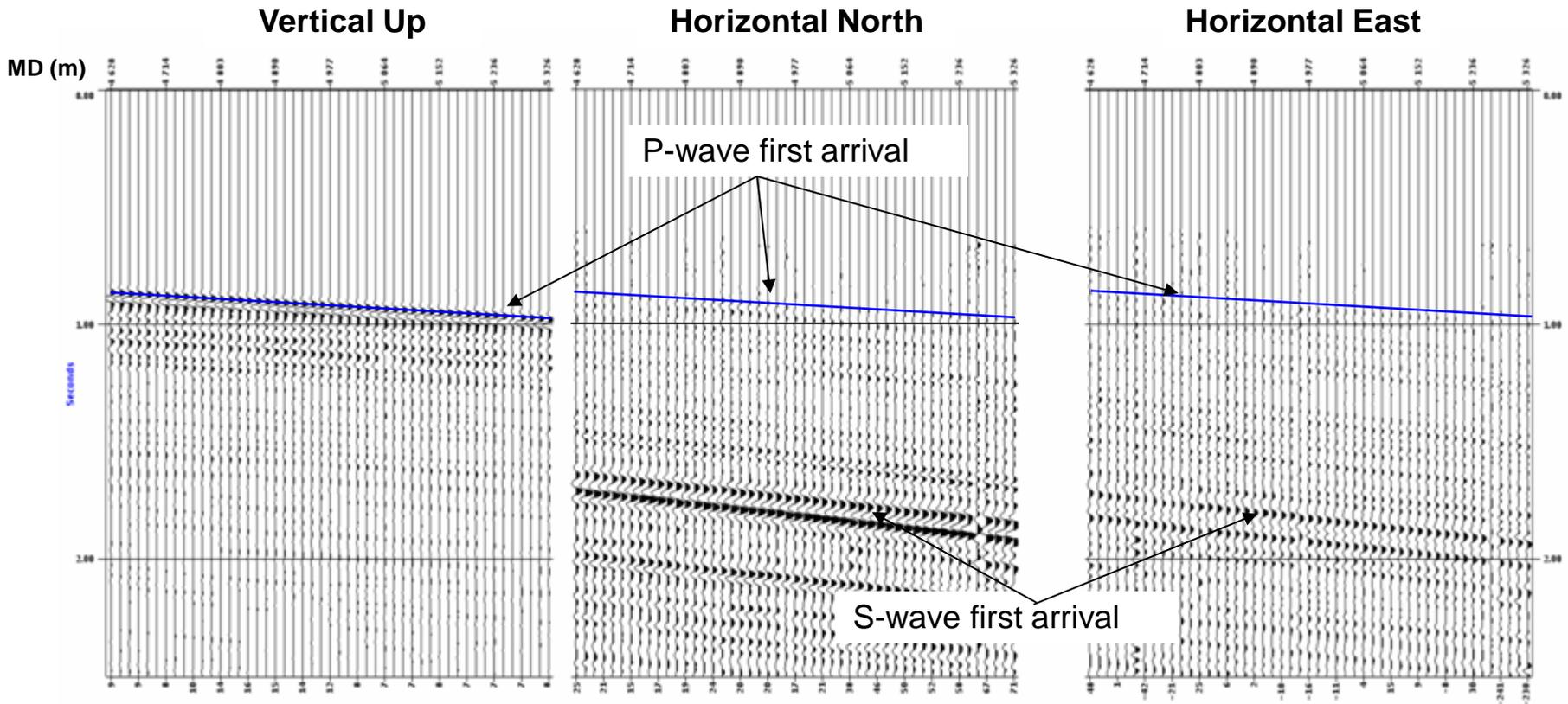
Courtesy of NIOC, IRAN

Raw 3C data Isotropic display 3 components



Courtesy of NIOC, IRAN

Oriented 3C data Isotropic display 3 components



P-wave direct arrival on Vertical component only,
S-wave direct arrival on horizontal components only